Learning Linear Bayesian Networks with Latent Variables

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Modern data

- Lots of high-dimensional data, but highly structured.
- Learning the underlying structure is central to:
 - Modeling
 - Dimensionality reduction/ summarizing data
 - Prediction

Fhis talk: Learning hidden (unobserved) variables that pervaded the data.

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This talk:

Learning hidden (unobserved) variables that pervaded the data.

Example: document modeling



Observations: words

Hidden variables: topics

Topics

genome molecular sequence DNA human genetics map project disease tuberculosis penumonia control doctor weak resistance fatal

software system parallel hardware cyber network data program

Example: social network modeling



Observations: social interactions Hidden: communities, relationships

Example: bio-informatics



Observations: gene expressions Hidden variables: gene regulators

Linear Bayesian Network

Markov relationship on DAG

- PA_i : parents of node *i*.
- $\mathbb{P}_{\theta}(z) = \prod_{i=1}^{n} \mathbb{P}_{\theta}(z_i | z_{\mathsf{PA}_i}).$



Linear model with latent nodes

- Observed variables $\{x_i\}$ and hidden variables $\{h_i\}$.
- Linear relations: $x_i = \sum_{j \in \mathsf{PA}_i} a_{ij} h_j + \epsilon_i$
- uncorrelated noise variables ϵ_i

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Learning latent models

Goal: Given the observed data, learn structure and parameters of model.

Challenges:

- Identifiablity Many models can explain the observed data!
 - ICA: no edge between hidden nodes
 - LDA: hidden variables are drawn from a Dirichlet distribution
 - latent trees, graphical models with long cycles.
 [Anandkumar et.al. 2011, Choi et. al. 2011, Daskalakis et. al. 2006]

Tractable learning algorithms:

- Maximum likelihood (tractable on trees, NP-hard in general)
- Expectation maximization [Redner, Walker 1984], Gibbs sampling [Asuncion et. al. 2011]
- Local tests [Bresler et. al. 2008, Anadkumar et. al. 2012,]
- Convex relaxations (e.g. Lasso) [Meinshausen, Bühlmann 2006, Ravikumar, Wainwright 2010]

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$$egin{cases} x &= Ah + \epsilon \ h &= \Lambda h + \eta \end{cases} \Longrightarrow x = A(I - \Lambda)^{-1}\eta + \epsilon$$



A prudent restriction on the model



Sufficient conditions for identifiability

Task: Recover A

Structural Condition: (Additive) Graph Expansion

 $|\mathcal{N}(S)| \geq |S| + d_{ ext{max}}$, for all $S \subset \mathcal{H}$

Parametric Condition: Generic Parameters

 $\|Av\|_0 > |\mathcal{N}_A(\mathrm{supp}(v))| - |\mathrm{supp}(v)|$

Identifiability result

Under above conditions, A can be uniquely recovered from $\mathbb{E}[xx^{\mathsf{T}}]$



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[Spielman, Wang, Wright 2012]

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- ▶ For non-degenerate $\mathbb{E}[hh^T]$, we know $\operatorname{Col}(A)$.
- ▶ Under above conditions, sparsest vectors in Col(A) are columns of A.

Exhaustive search
• Let
$$U = \operatorname{Col}(A\mathbb{E}[hh^{\mathsf{T}}]A^{\mathsf{T}})$$

• $\min_{z \neq 0} ||Uz||_0$

A tractable algorithm

Task: Recover A from $U = \text{Col}(A\mathbb{E}[hh^{\top}]A^{\mathsf{T}})$.



Under "reasonable" conditions, the above program exactly recovers A

Learning latent space parameters

Recall so far ...

Recovered A

- from second order moment $\mathbb{E}[xx^{\mathsf{T}}]$
- under no assumption on the hidden variables!

What hidden structures can be learnt from low order observed moments?

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What hidden structures can be learnt from low order observed moments?



$$\mathbb{E}[xx^\mathsf{T}] = A\mathbb{E}[hh^\mathsf{T}]A^\mathsf{T} + \mathbb{E}[\epsilon\epsilon^\mathsf{T}]$$



 $A\mathbb{E}[hh^{\mathsf{T}}]A^{\mathsf{T}}$



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 $A^{\dagger}A\mathbb{E}[hh^{\mathsf{T}}]A^{\mathsf{T}}(A^{\dagger})^{\mathsf{T}}$



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$\tilde{A}\mathbb{E}[\tilde{h}\tilde{h}^{\mathsf{T}}]\tilde{A}^{\mathsf{T}}$



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$\tilde{A}^{\dagger} \tilde{A} \mathbb{E}[\tilde{h} \tilde{h}^{\mathsf{T}}] \tilde{A}^{\mathsf{T}} (\tilde{A}^{\dagger})^{\mathsf{T}}$



$\mathbb{E}[\tilde{h}\tilde{h}^{\mathsf{T}}]$

• Recall
$$x = Ah + \epsilon$$

- Now additionally A is full rank (each hidden nodes has at least one observed neighbor)
- ► Linear dependence among hidden node: $h_j = \sum_{i \in \mathsf{PA}_j} \lambda_{ji} h_i + \eta_j$ (in matrix form $h = \Lambda h + \eta$)
- Noise variables η_j are uncorrelated.



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- Employ spectral approach to learn $A(I \Lambda)^{-1}$
 - second order moment:

$$\mathbb{E}[xx^{\mathsf{T}}] = A(I - \Lambda)^{-1}\mathbb{E}[\eta\eta^{\mathsf{T}}](A(I - \Lambda))^{\mathsf{T}} + \mathbb{E}[\epsilon\epsilon^{\mathsf{T}}]$$

third order moment:

$$\Big| \mathbb{E}[xx^{\mathsf{T}}\langle \xi, x\rangle] = A(I - \Lambda)^{-1} \mathbb{E}[\eta\eta^{\mathsf{T}}\langle \eta, A^{\mathsf{T}}\xi\rangle] (A(I - \Lambda))^{\mathsf{T}} + \mathbb{E}[\epsilon\epsilon^{\mathsf{T}}\langle \xi, \epsilon\rangle]$$

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 Simultaneous diagonalization of the moments (through SVD or tensor decompositions)

[Anandkumar, Foster, Hsu, Kakade, Liu 2012]

[Anandkumar, Ge, Hsu, Kakade 2012]

• "
$$\operatorname{Col}(A) = \operatorname{Col}(A(I - \Lambda)^{-1})$$
" + "expansion property" $\Rightarrow A$ and Λ

- k = 25 hidden nodes and n = 150 observed nodes
- Bernoulli-Gaussian model (p = 0.3), total number of edges = 1177.
- Noise variables distributed as exponential, poisson, chi-2, Gaussian with mean zero and variances chosen randomly in [0.5, 1].

number of samples = 25,000



number of samples = 100,000



number of samples = 400,000



Conclusion

- Considered learning latent models with arbitrary hidden variable dependencies.
- Constraint on the model: expansion of bipartite graph from hidden to observed layer, generic parameter and non-degeneracy.
- Established identifiability of A under no assumption but non-degeneracy of the hidden variables!
- Recovering A through ℓ_1 optimization.
- Can be used to learn topic-word matrix under the expansion constraint and arbitrary topic dependencies.
- Learning the hidden space parameters and structure for multi-level DAGs and linear structural equations.

You are welcome to visit our poster presentation (Paper ID: 146)!

Thanks!