

Minimax risk of truncated series estimators over symmetric convex polytopes

Adel Javanmard (Stanford University)
with Li Zhang (Microsoft Research)

July 4, 2012

Motivation: function estimation

Consider a continuous function $f : [0, 1] \rightarrow \mathbb{R}$.

We have measurements

$$y_i = f(t_i) + w_i, \quad \text{for } 1 \leq i \leq n.$$

Estimate $\{f(t_i)\}_{i=1}^n$ under linear inequality constraints:

$$x = (f(t_1), \dots, f(t_n))$$

$$Ax \leq b$$

- ▶ Lipschitz constraint:

$$|x_{i+1} - x_i| \leq L|t_{i+1} - t_i| \text{ for } 1 \leq i \leq n - 1.$$

- ▶ General convex constraints

What is a good estimator?

Motivation: function estimation

Consider a continuous function $f : [0, 1] \rightarrow \mathbb{R}$.

We have measurements

$$y_i = f(t_i) + w_i, \quad \text{for } 1 \leq i \leq n.$$

Estimate $\{f(t_i)\}_{i=1}^n$ under linear inequality constraints:

$$x = (f(t_1), \dots, f(t_n))$$

$$Ax \leq b$$

- ▶ Lipschitz constraint:

$$|x_{i+1} - x_i| \leq L|t_{i+1} - t_i| \text{ for } 1 \leq i \leq n - 1.$$

- ▶ General convex constraints

What is a good estimator?

Motivation: function estimation

Consider a continuous function $f : [0, 1] \rightarrow \mathbb{R}$.

We have measurements

$$y_i = f(t_i) + w_i, \quad \text{for } 1 \leq i \leq n.$$

Estimate $\{f(t_i)\}_{i=1}^n$ under linear inequality constraints:

$$x = (f(t_1), \dots, f(t_n))$$

$$Ax \leq b$$

- ▶ Lipschitz constraint:

$$|x_{i+1} - x_i| \leq L|t_{i+1} - t_i| \text{ for } 1 \leq i \leq n - 1.$$

- ▶ General convex constraints

What is a good estimator?

Motivation: function estimation

Consider a continuous function $f : [0, 1] \rightarrow \mathbb{R}$.

We have measurements

$$y_i = f(t_i) + w_i, \quad \text{for } 1 \leq i \leq n.$$

Estimate $\{f(t_i)\}_{i=1}^n$ under linear inequality constraints:

$$x = (f(t_1), \dots, f(t_n))$$

$$Ax \leq b$$

- ▶ Lipschitz constraint:

$$|x_{i+1} - x_i| \leq L|t_{i+1} - t_i| \quad \text{for } 1 \leq i \leq n - 1.$$

- ▶ General convex constraints

What is a good estimator?

General problem

$$y = x + w,$$

$$x \in X \subseteq \mathbb{R}^n, \quad w \sim N(0, \sigma^2 I_{n \times n}).$$

For any estimator $M : \mathbb{R}^n \rightarrow \mathbb{R}^n$, define

$$R(M, X, \sigma) = \max_{x \in X} \mathbb{E}_{y \sim x+w} \|x - M(y)\|^2.$$

Minimax risk of a set

$$R(X, \sigma) = \min_M R(M, X, \sigma).$$

General problem

$$y = x + w,$$

$$x \in X \subseteq \mathbb{R}^n, \quad w \sim N(0, \sigma^2 I_{n \times n}).$$

For any estimator $M : \mathbb{R}^n \rightarrow \mathbb{R}^n$, define

$$R(M, X, \sigma) = \max_{x \in X} \mathbb{E}_{y \sim x+w} \|x - M(y)\|^2.$$

Minimax risk of a set

$$R(X, \sigma) = \min_M R(M, X, \sigma).$$

Classes of estimators

- ▶ **Nonlinear estimators:**

The estimator M can be generally nonlinear. $R(X, \sigma)$

Classes of estimators

- ▶ **Nonlinear estimators:**

The estimator M can be generally nonlinear. $R(X, \sigma)$

- ▶ **Linear estimators:**

When M is linear, we denote the minimax risk by $R_L(X, \sigma)$

Classes of estimators

- ▶ **Nonlinear estimators:**

The estimator M can be generally nonlinear. $R(X, \sigma)$

- ▶ **Linear estimators:**

When M is linear, we denote the minimax risk by $R_L(X, \sigma)$

- ▶ **Truncated series estimators:**

Especial class of linear estimators given by orthogonal projections

$$M(y) = Py.$$

The minimax risk is denoted by $R_T(X, \sigma)$.

Classes of estimators

- ▶ **Nonlinear estimators:**

The estimator M can be generally nonlinear. $R(X, \sigma)$

- ▶ **Linear estimators:**

When M is linear, we denote the minimax risk by $R_L(X, \sigma)$

- ▶ **Truncated series estimators:**

Especial class of linear estimators given by orthogonal projections

$$M(y) = Py.$$

The minimax risk is denoted by $R_T(X, \sigma)$.

$$R(X, \sigma) \leq R_L(X, \sigma) \leq R_T(X, \sigma).$$

$$X \subseteq Y \Rightarrow R(X, \sigma) \leq R(Y, \sigma).$$

Challenges

- ▶ How to compute the minimax risk for arbitrary convex bodies?
- ▶ How to design the minimax optimal estimator?

Related work

- ▶ Minimax bounds have been developed for various families:
 - Orthosymmetric and quadratically convex objects:
Hypercubes, ellipsoids, ℓ_p balls for $p \geq 2$.
[Donoho, Liu, MacGibbon'90]
 - Class of Hölder balls, Sobolev balls, and Besov balls
(continuity and energy conditions)
[Tsybakov'09]

- ▶ Techniques for bounding the minimax risk
[Donoho'90, Nemirovski'99, Yang, Barron'99]

Our main contributions

- ▶ A lower bound for minimax risk
 - based on a geometric quantity of the set (approximation radius)
 - depends on the volume of the set (intuitive and strong bounds)

- ▶ Optimality of truncated estimators over symmetric polytopes

information theory tools → geometrical understanding of minimax risks

Our main contributions

- ▶ A lower bound for minimax risk
 - based on a geometric quantity of the set (approximation radius)
 - depends on the volume of the set (intuitive and strong bounds)

- ▶ Optimality of truncated estimators over symmetric polytopes

information theory tools → geometrical understanding of minimax risks

Our main contributions

- ▶ A lower bound for minimax risk
 - based on a geometric quantity of the set (approximation radius)
 - depends on the volume of the set (intuitive and strong bounds)

- ▶ Optimality of truncated estimators over symmetric polytopes

information theory tools → geometrical understanding of minimax risks

Outline

- 1 Main result
- 2 An application
- 3 Proof techniques
- 4 Further comments

Main result

Notation

For $p > 0$ and $m, n \geq 1$, let

$$\mathcal{F}_p^{m,n} = \{X : X = \{x : \|Ax\|_p \leq 1\}, \text{ for } A \in \mathbb{R}^{m \times n}\}$$

$\mathcal{F}_\infty^{m,n}$: Family of symmetric polytopes defined by m hyperplanes

Definition

$$\beta(X) = \max_{\sigma > 0} \frac{R_T(X, \sigma)}{R(X, \sigma)}, \quad \beta_p^{m,n} = \max_{X \in \mathcal{F}_p^{m,n}} \beta(X).$$

Notation

For $p > 0$ and $m, n \geq 1$, let

$$\mathcal{F}_p^{m,n} = \{X : X = \{x : \|Ax\|_p \leq 1\}, \text{ for } A \in \mathbb{R}^{m \times n}\}$$

$\mathcal{F}_\infty^{m,n}$: Family of symmetric polytopes defined by m hyperplanes

Definition

$$\beta(X) = \max_{\sigma > 0} \frac{R_T(X, \sigma)}{R(X, \sigma)}, \quad \beta_p^{m,n} = \max_{X \in \mathcal{F}_p^{m,n}} \beta(X).$$

Notation

For $p > 0$ and $m, n \geq 1$, let

$$\mathcal{F}_p^{m,n} = \{X : X = \{x : \|Ax\|_p \leq 1\}, \text{ for } A \in \mathbb{R}^{m \times n}\}$$

$\mathcal{F}_\infty^{m,n}$: Family of symmetric polytopes defined by m hyperplanes

Definition

$$\beta(X) = \max_{\sigma > 0} \frac{R_T(X, \sigma)}{R(X, \sigma)}, \quad \beta_p^{m,n} = \max_{X \in \mathcal{F}_p^{m,n}} \beta(X).$$

Optimality of truncated estimators

Theorem (Javanmard, Zhang '11)

If $n = \Omega(\log m)$, for some universal constant C we have

$$\beta_{\infty}^{m,n} \leq C \log m.$$

Furthermore, $\beta_{\infty}^{m,n} = \Omega(\sqrt{\log m / \log \log m})$.

[Recall:

$a = \Omega(b)$ if a is bounded below by b (up to a constant factor) asymptotically]

An application

Function estimation

Consider a univariate Lipschitz function $f : [0, 1] \rightarrow \mathbb{R}$.

We have measurements

$$y_i = f(t_i) + w_i, \quad \text{for } 1 \leq i \leq n.$$

Goal: estimate $\{f(t_i)\}_{i=1}^n$ from measurements $\{y_i\}_{i=1}^n$.

Lipschitz condition (with constant L):

$$|f(t_{i+1}) - f(t_i)| \leq L|t_{i+1} - t_i|, \quad \text{for } 1 \leq i \leq n - 1.$$

Previous work shows near-optimality of truncated estimators for **uniform** sampling.

[Nemirovski, Tsybakov'09]

Function estimation

Consider a univariate Lipschitz function $f : [0, 1] \rightarrow \mathbb{R}$.

We have measurements

$$y_i = f(t_i) + w_i, \quad \text{for } 1 \leq i \leq n.$$

Goal: estimate $\{f(t_i)\}_{i=1}^n$ from measurements $\{y_i\}_{i=1}^n$.

Lipschitz condition (with constant L):

$$|f(t_{i+1}) - f(t_i)| \leq L|t_{i+1} - t_i|, \quad \text{for } 1 \leq i \leq n - 1.$$

Corollary of our theorem

The truncated series estimator is nearly optimal (within $O(\log n)$) for estimating Lipschitz function at **arbitrary** sample set.

Proof techniques

high-level idea

- ▶ We choose a family of **obstruction objects** for which we know tight lower bound of minimax risk.
- ▶ For $X \in \mathcal{F}_\infty^{m,n}$, we show that if X does not have a good truncated estimator, then it will have a “large” obstruction. Hence, no estimator can do well on X .

The difficulty is in choosing the right obstruction for the desired result.

high-level idea

- ▶ We choose a family of **obstruction objects** for which we know tight lower bound of minimax risk.
- ▶ For $X \in \mathcal{F}_\infty^{m,n}$, we show that if X does not have a good truncated estimator, then it will have a “large” obstruction. Hence, no estimator can do well on X .

The difficulty is in choosing the right obstruction for the desired result.

Natural obstructions

Euclidean balls

Hyper-rectangles

Natural obstructions

Euclidean balls



Hyper-rectangles



Not suitable for skewed polytopes!

A remedy : notion of approximation radius

Obstructions: Family of objects which contain a “non-negligible” fraction of a “large” ball.

What does it mean formally?

For any $r > 0$, the volume ratio $\text{vr}(X, r)$ is defined as

$$\text{vr}(X, r) = \left(\frac{\text{vol}(X \cap B_2^n(r))}{\text{vol}(B_2^n(r))} \right)^{1/n}.$$

k -volume ratio $\text{vr}_k(X, r)$:

$$\text{vr}_k(X, r) = \max_{H \in \mathcal{H}_n^k} \text{vr}(X \cap H, r).$$

A remedy : notion of approximation radius

Obstructions: Family of objects which contain a “non-negligible” fraction of a “large” ball.

What does it mean formally?

For any $r > 0$, the volume ratio $\text{vr}(X, r)$ is defined as

$$\text{vr}(X, r) = \left(\frac{\text{vol}(X \cap B_2^n(r))}{\text{vol}(B_2^n(r))} \right)^{1/n}.$$

k -volume ratio $\text{vr}_k(X, r)$:

$$\text{vr}_k(X, r) = \max_{H \in \mathcal{H}_n^k} \text{vr}(X \cap H, r).$$

A remedy : notion of approximation radius

Obstructions: Family of objects which contain a “non-negligible” fraction of a “large” ball.

What does it mean formally?

For any $r > 0$, the volume ratio $\text{vr}(X, r)$ is defined as

$$\text{vr}(X, r) = \left(\frac{\text{vol}(X \cap B_2^n(r))}{\text{vol}(B_2^n(r))} \right)^{1/n}.$$

k -volume ratio $\text{vr}_k(X, r)$:

$$\text{vr}_k(X, r) = \max_{H \in \mathcal{H}_n^k} \text{vr}(X \cap H, r).$$

Approximation radius and a lower bound

Definition (Approximation radius)

For $0 \leq c \leq 1$, and integer $1 \leq k \leq n$, the (c, k) -approximation radius of X , denoted by $z_{c,k}(X)$ is defined as

$$z_{c,k} = \sup\{r : \text{vr}_k(X, r) \geq c\}.$$

Theorem (Javanmard, Zhang '11)

For any convex set X , and any $0 < c_* \leq 1$,

$$R(X, \sigma) \geq Cc_*^2 \max_{0 \leq k \leq n} \min\{z_{c_*,k}(X)^2, k\sigma^2\}.$$

Here, C is a universal constant.

Proof:

Fano's inequality and a lower bound established by Yang, Barron '99.

Approximation radius and a lower bound

Definition (Approximation radius)

For $0 \leq c \leq 1$, and integer $1 \leq k \leq n$, the (c, k) -approximation radius of X , denoted by $z_{c,k}(X)$ is defined as

$$z_{c,k} = \sup\{r : \text{vr}_k(X, r) \geq c\}.$$

Theorem (Javanmard, Zhang '11)

For any convex set X , and any $0 < c_* \leq 1$,

$$R(X, \sigma) \geq Cc_*^2 \max_{0 \leq k \leq n} \min\{z_{c_*,k}(X)^2, k\sigma^2\}.$$

Here, C is a universal constant.

Proof:

Fano's inequality and a lower bound established by Yang, Barron '99.

Kolmogorov widths and truncated estimators

$$y = x + w, \quad M(y) = Py.$$

Let $P \in \mathcal{P}_k$ (the set of k -dimensional projections), then

$$\begin{aligned} \mathbb{E} \|x - M(y)\|^2 &= \mathbb{E} (\|x - P(x)\|^2 + \|P(w)\|^2) \\ &= \|x - P(x)\|^2 + k\sigma^2. \end{aligned}$$

k - Kolmogorov width:

$$d_k(X) = \min_{P \in \mathcal{P}_k} \max_{x \in X} \|x - Px\| = \min_{P \in \mathcal{P}_k} \max_{x \in X} \|P^\perp x\|.$$

k - Kolmogorov widths characterize the risk!

$$R_T(X, \sigma) = \min_k (d_k(X)^2 + k\sigma^2).$$

Kolmogorov widths and truncated estimators

$$y = x + w, \quad M(y) = Py.$$

Let $P \in \mathcal{P}_k$ (the set of k -dimensional projections), then

$$\begin{aligned} \mathbb{E} \|x - M(y)\|^2 &= \mathbb{E} (\|x - P(x)\|^2 + \|P(w)\|^2) \\ &= \|x - P(x)\|^2 + k\sigma^2. \end{aligned}$$

k - Kolmogorov width:

$$d_k(X) = \min_{P \in \mathcal{P}_k} \max_{x \in X} \|x - Px\| = \min_{P \in \mathcal{P}_k} \max_{x \in X} \|P^\perp x\|.$$

k - Kolmogorov widths characterize the risk!

$$R_T(X, \sigma) = \min_k (d_k(X)^2 + k\sigma^2).$$

Kolmogorov widths and truncated estimators

$$y = x + w, \quad M(y) = Py.$$

Let $P \in \mathcal{P}_k$ (the set of k -dimensional projections), then

$$\begin{aligned} \mathbb{E} \|x - M(y)\|^2 &= \mathbb{E} (\|x - P(x)\|^2 + \|P(w)\|^2) \\ &= \|x - P(x)\|^2 + k\sigma^2. \end{aligned}$$

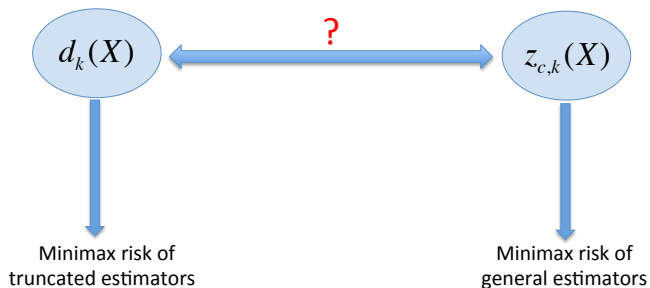
k - Kolmogorov width:

$$d_k(X) = \min_{P \in \mathcal{P}_k} \max_{x \in X} \|x - Px\| = \min_{P \in \mathcal{P}_k} \max_{x \in X} \|P^\perp x\|.$$

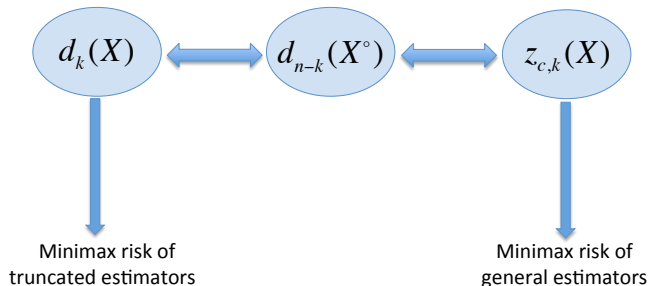
k - Kolmogorov widths characterize the risk!

$$R_T(X, \sigma) = \min_k (d_k(X)^2 + k\sigma^2).$$

Schematic



Schematic



A duality relationship

Lemma (Javanmard, Zhang '11)

For any convex symmetric $X \subset \mathbb{R}^n$ and any $0 \leq k \leq n$ and $0 < \epsilon < 1$,

$$d_k(X) d_{n-(1-\epsilon)k}(X^\circ) \leq c_1 \sqrt{\frac{k}{\epsilon}},$$

where $c_1 > 0$ is a universal constant.

X contains a k -dimensional ball with radius $1/d_{n-k}(X^\circ)$.

$$d_k(X) \leq c_1 \sqrt{\frac{k}{\epsilon}} \frac{1}{d_{n-(1-\epsilon)k}(X^\circ)}$$

\implies gives a fairly weak bound on $R_T(X, \sigma) :$

A duality relationship

Lemma (Javanmard, Zhang '11)

For any convex symmetric $X \subset \mathbb{R}^n$ and any $0 \leq k \leq n$ and $0 < \epsilon < 1$,

$$d_k(X) d_{n-(1-\epsilon)k}(X^\circ) \leq c_1 \sqrt{\frac{k}{\epsilon}},$$

where $c_1 > 0$ is a universal constant.

X contains a k -dimensional ball with radius $1/d_{n-k}(X^\circ)$.

$$d_k(X) \leq c_1 \sqrt{\frac{k}{\epsilon}} \frac{1}{d_{n-(1-\epsilon)k}(X^\circ)}$$

\implies gives a fairly weak bound on $R_T(X, \sigma) :$

A duality relationship

Lemma (Javanmard, Zhang '11)

For any convex symmetric $X \subset \mathbb{R}^n$ and any $0 \leq k \leq n$ and $0 < \epsilon < 1$,

$$d_k(X) d_{n-(1-\epsilon)k}(X^\circ) \leq c_1 \sqrt{\frac{k}{\epsilon}},$$

where $c_1 > 0$ is a universal constant.

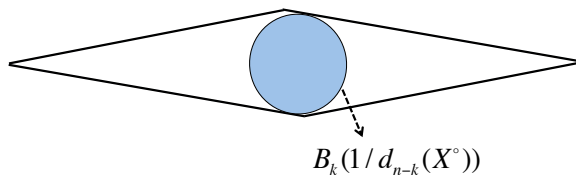
X contains a k -dimensional ball with radius $1/d_{n-k}(X^\circ)$.

$$d_k(X) \leq c_1 \sqrt{\frac{k}{\epsilon}} \frac{1}{d_{n-(1-\epsilon)k}(X^\circ)}$$

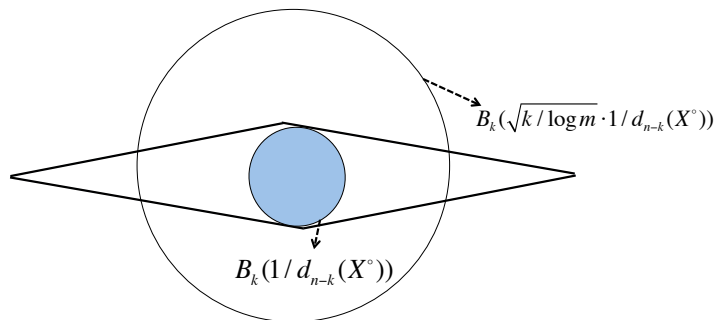
\implies gives a fairly weak bound on $R_T(X, \sigma) :$

... and relation to the approximation radius

Suppose $X \in \mathcal{F}_{\infty}^{m,n}$.



... and relation to the approximation radius



Larger ball still has non-negligible fraction of its volume inside X .

Final step

Lemma (Javanmard, Zhang '11)

For any $X \in \mathcal{F}_\infty^{m,n}$, $0 < c_* \leq 0.2$, and $0 < k \leq n$,

$$z_{c_*,k}(X) \geq c_2 \sqrt{\frac{k}{\log m}} \cdot \frac{1}{d_{n-k}(X^\circ)},$$

where c_2 is a universal constant.

Combining the lemmas,

$$d_k(X) \leq c_1 \sqrt{\frac{k}{\epsilon}} \cdot \frac{1}{d_{n-(1-\epsilon)k}(X^\circ)} \leq c_1 c_2 \sqrt{\frac{\log m}{\epsilon}} z_{c_*,k}(X).$$

Skinny objects always have a small shadow!

Final step

Lemma (Javanmard, Zhang '11)

For any $X \in \mathcal{F}_\infty^{m,n}$, $0 < c_* \leq 0.2$, and $0 < k \leq n$,

$$z_{c_*,k}(X) \geq c_2 \sqrt{\frac{k}{\log m}} \cdot \frac{1}{d_{n-k}(X^\circ)},$$

where c_2 is a universal constant.

Combining the lemmas,

$$d_k(X) \leq c_1 \sqrt{\frac{k}{\epsilon}} \cdot \frac{1}{d_{n-(1-\epsilon)k}(X^\circ)} \leq c_1 c_2 \sqrt{\frac{\log m}{\epsilon}} z_{c_*,k}(X).$$

Skinny objects always have a small shadow!

Further comments

What about $\beta_p^{m,n}$?

[Recall:

$$\beta_p^{m,n} = \max_{X \in \mathcal{F}_p^{m,n}} \max_{\sigma > 0} \frac{R_T(X, \sigma)}{R(X, \sigma)},$$

$$\mathcal{F}_p^{m,n} = \{X : X = \{x : \|Ax\|_p \leq 1\}, \text{ for } A \in \mathbb{R}^{m \times n}\}. \quad]$$

Corollary

For $p \geq 2$, $\beta_p^{m,n} = O(\min(n^{1-2/p}, m^{2/p} \log m))$.

Conjecture: For any $p \geq 2$, there exists a constant $C = C(p)$, such that $\beta_p^{m,n} \leq C \log m$.

What about $\beta_p^{m,n}$?

[Recall:

$$\beta_p^{m,n} = \max_{X \in \mathcal{F}_p^{m,n}} \max_{\sigma > 0} \frac{R_T(X, \sigma)}{R(X, \sigma)},$$

$$\mathcal{F}_p^{m,n} = \{X : X = \{x : \|Ax\|_p \leq 1\}, \text{ for } A \in \mathbb{R}^{m \times n}\}. \quad]$$

Corollary

For $p \geq 2$, $\beta_p^{m,n} = O(\min(n^{1-2/p}, m^{2/p} \log m))$.

Conjecture: For any $p \geq 2$, there exists a constant $C = C(p)$, such that $\beta_p^{m,n} \leq C \log m$.

What about $\beta_p^{m,n}$?

[Recall:

$$\beta_p^{m,n} = \max_{X \in \mathcal{F}_p^{m,n}} \max_{\sigma > 0} \frac{R_T(X, \sigma)}{R(X, \sigma)},$$

$$\mathcal{F}_p^{m,n} = \{X : X = \{x : \|Ax\|_p \leq 1\}, \text{ for } A \in \mathbb{R}^{m \times n}\}. \quad]$$

Corollary

For $p \geq 2$, $\beta_p^{m,n} = O(\min(n^{1-2/p}, m^{2/p} \log m))$.

Conjecture: For any $p \geq 2$, there exists a constant $C = C(p)$, such that $\beta_p^{m,n} \leq C \log m$.

Design problem

How to design optimal truncated series estimators for symmetric polytopes?

- ▶ NP-hard in general \rightarrow SDP formulations to solve a relaxation

Thanks!

Design problem

How to design optimal truncated series estimators for symmetric polytopes?

- ▶ NP-hard in general \rightarrow SDP formulations to solve a relaxation

Thanks!